

# Wireless Sensor Networks

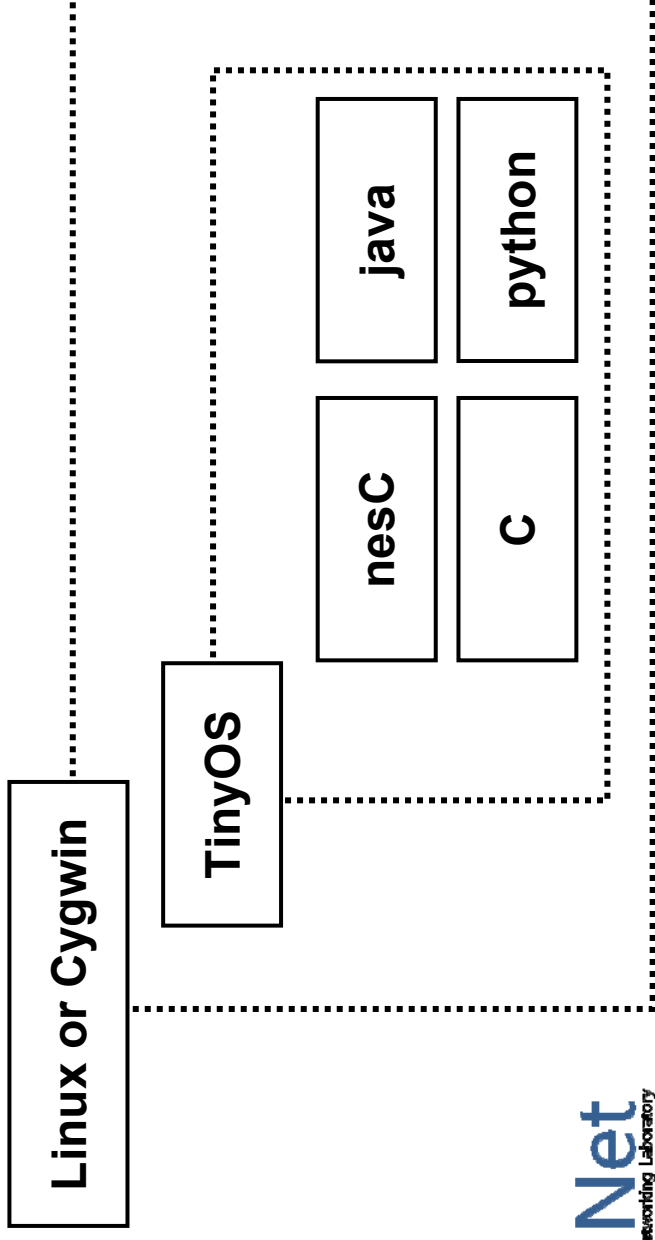
## Blink Example

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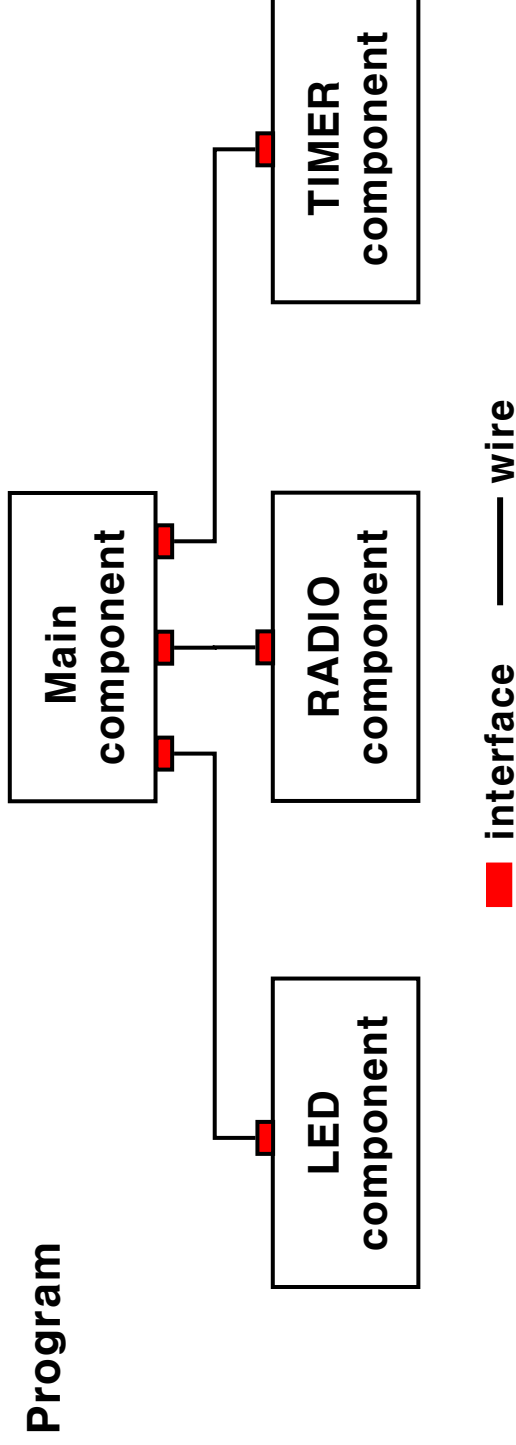
# Introduction of TinyOS

- TinyOS is an unique Operating System (OS) for small wireless sensing devices
- Development environment of TinyOS is Linux
- Windows user uses Cygwin to make virtual linux environment
- C /nesc / python are used for TinyOS programming
- Nesc is used mainly



# NesC

- NesC is extension of C language and component-based
- A TinyOS program consists of components and interfaces



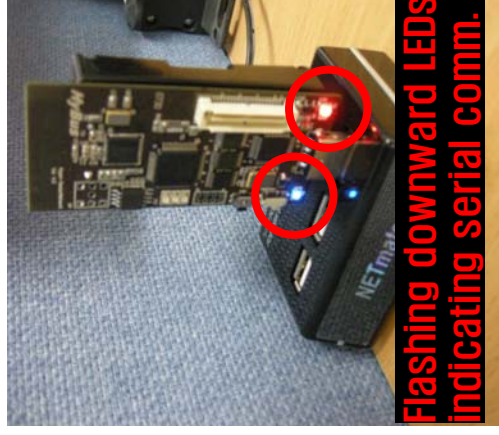
# Blink Example

- \$ cd /opt/tinyos-2.x/apps/Blink
- \$ make hybus install

```

Administrator@busn-fb4e2fe795f6 /opt/tinyos-2.x/apps/Blink
$ make hybus install
mk...
compiling BlinkAppC to a hybus binary
ncc -o build/hybus/main.exe -Os -O -mdisable-hwmul -Wall -fild/hybus/app.c -board= -DIDENT_PROGRAM_NAME="#BlinkAppC#" -DIDENT_USER_HASH=0x9a82d3bdL -DIDENT_UNIX_TIME=0x47d64885L compiled BlinkAppC to build/hybus/main.exe
2588 bytes in ROM
55 bytes in RAM
msp430-objcopy --output-target=ihex build/hybus/main.exe build/hybus/main.ihex
wri
Compiling & Assembling...nex.out
cp build/hybus/main.ihex build/hybus/main.exe
found note on COM55 (using bsl.auto)
installing hybus binary using bsl
tos-bsl --telos -c 54 -r -e -l -p build/hybus/main.ihex.out
MSP430 Bootstrap Loader Version: 1.39-telos-8
Mass Erase...
Transmit default password ...
Invoking BSL...
Transmit default password ...
Current bootstrap loader version: 1.61 (Device ID: f16c)
Program ...
2612 bytes program
Reset device ...
rm -f build/hybus/main.exe.out build/hybus/main.ihex.out

```



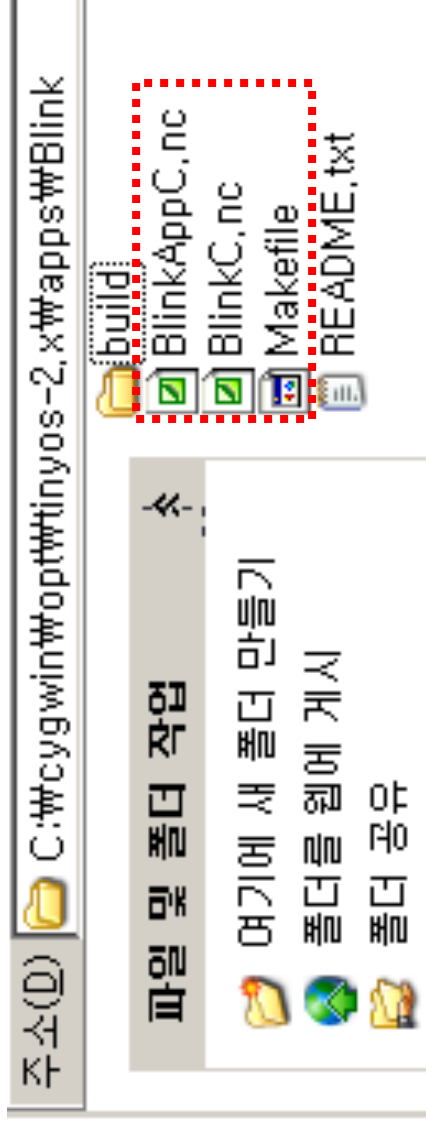
during uploading



after uploading

## Blink Example (Cont.)

- There are three important files:
  - BlinkAppC.nc (configuration)
  - BlinkC.nc (module)
  - Makefile (for gcc compiler)



# Blink Example (Cont.)

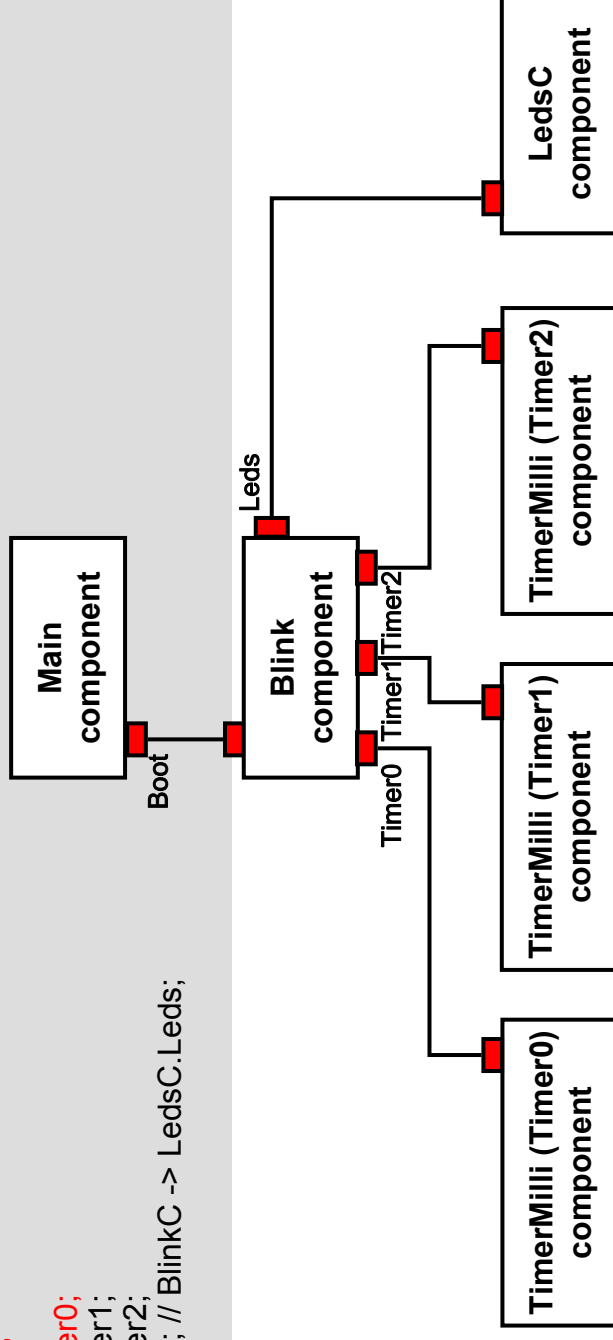
```

BlinkAppC.nc
configuration BlinkAppC
{
}
implementation
{
    components MainC, BlinkC, LedsC;
    components new TimerMilliC() as Timer0;
    components new TimerMilliC() as Timer1;
    components new TimerMilliC() as Timer2;

    BlinkC -> MainC.Boot;

    BlinkC.Timer0 -> Timer0;
    BlinkC.Timer1 -> Timer1;
    BlinkC.Timer2 -> Timer2;
    BlinkC.Leds -> LedsC; // BlinkC -> LedsC.Leds;
}

```

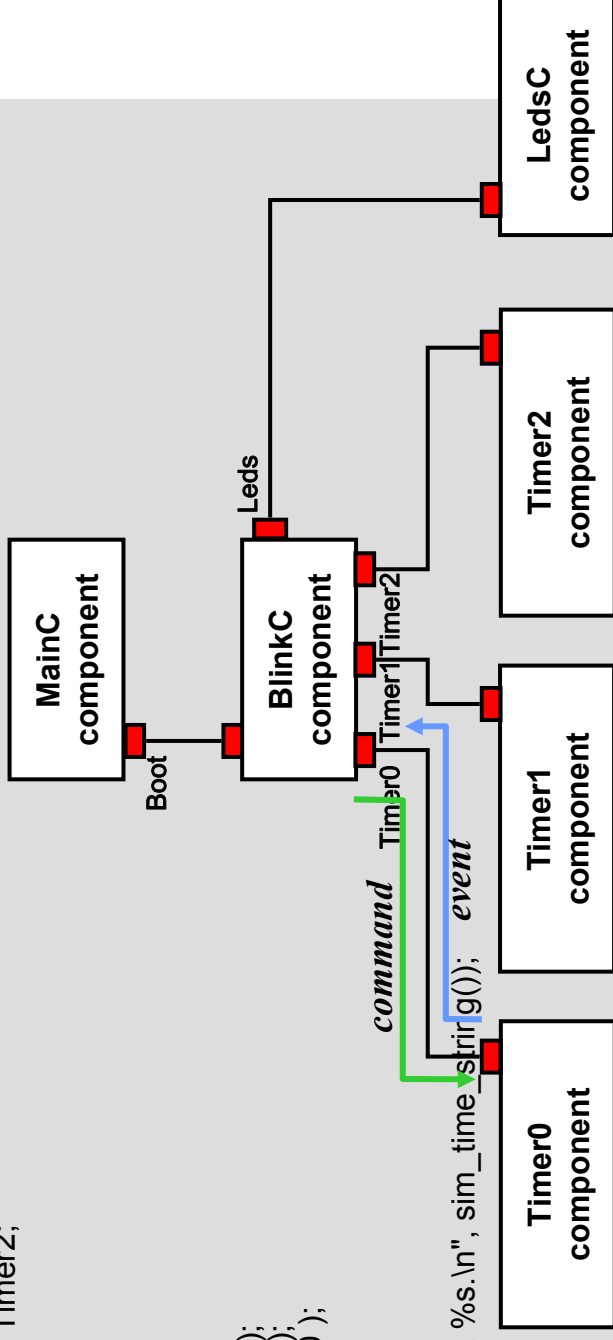


# Blink Example (Cont.)

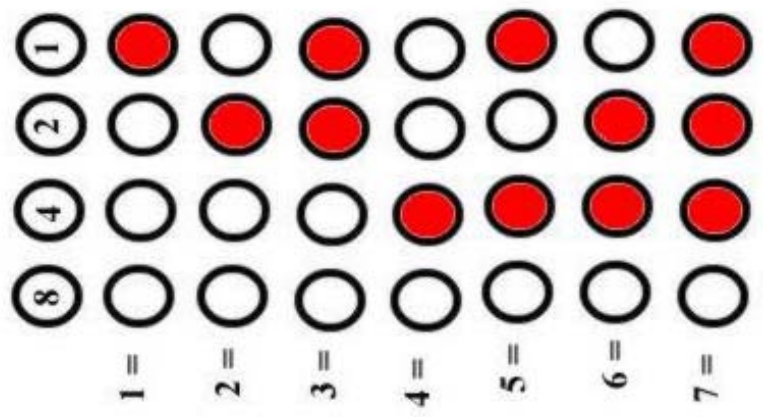
```

Blink.nc
module BlinkC @safe()
{
    uses interface Timer<TMilli> as Timer0;
    uses interface Timer<TMilli> as Timer1;
    uses interface Timer<TMilli> as Timer2;
    uses interface Leds;
    uses interface Boot;
}
implementation
{
    event void Boot.booted()
    {
        call Timer0.startPeriodic( 250 );
        call Timer1.startPeriodic( 500 );
        call Timer2.startPeriodic( 1000 );
    }
    event void Timer0.fired()
    {
        dbg("BlinkC", "Timer 0 fired @ %s.\n", sim_time_string());
        call Leds.led0Toggle();
    }
    event void Timer1.fired()
    {
        dbg("BlinkC", "Timer 1 fired @ %s.\n", sim_time_string());
        call Leds.led1Toggle();
    }
    event void Timer2.fired()
    {
        dbg("BlinkC", "Timer 2 fired @ %s.\n", sim_time_string());
        call Leds.led2Toggle();
    }
}

```



# Homework: With a Timer, make a binary counter





# Q and A